

Development of an LES-LPT based method for ice accretion simulation

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Wind Turbine Icing Research

- Where?
 - Icing maps
- Ice prevention
 - passive
 - active
- Detection and measurement

- How does the ice accrete?



- Measurements

- Computations

Modeling Ice Accretion

- Icing types
 - Glaze
 - Rime
- Makkonen [Makkonen1985]

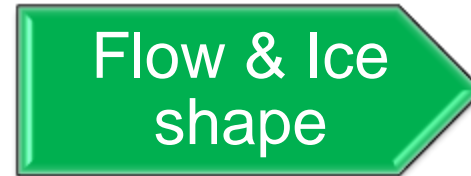
$$\frac{dM}{dt} = \alpha_1 \alpha_2 \alpha_3 \rho u A$$

- α_i – collision/sticking/accretion efficiency

• Strategies



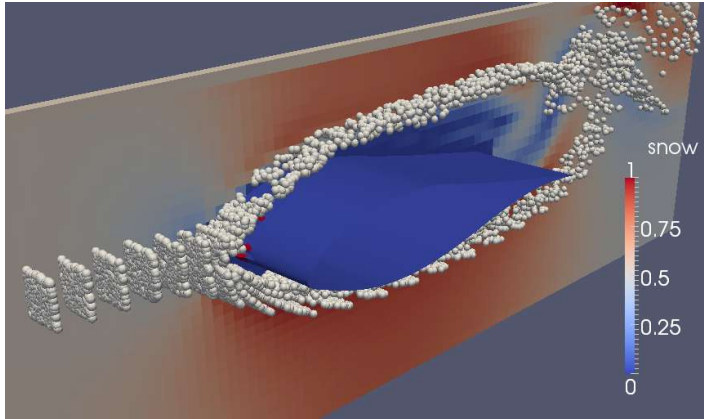
LEWICE, TURBICE



FENSAP-ICE



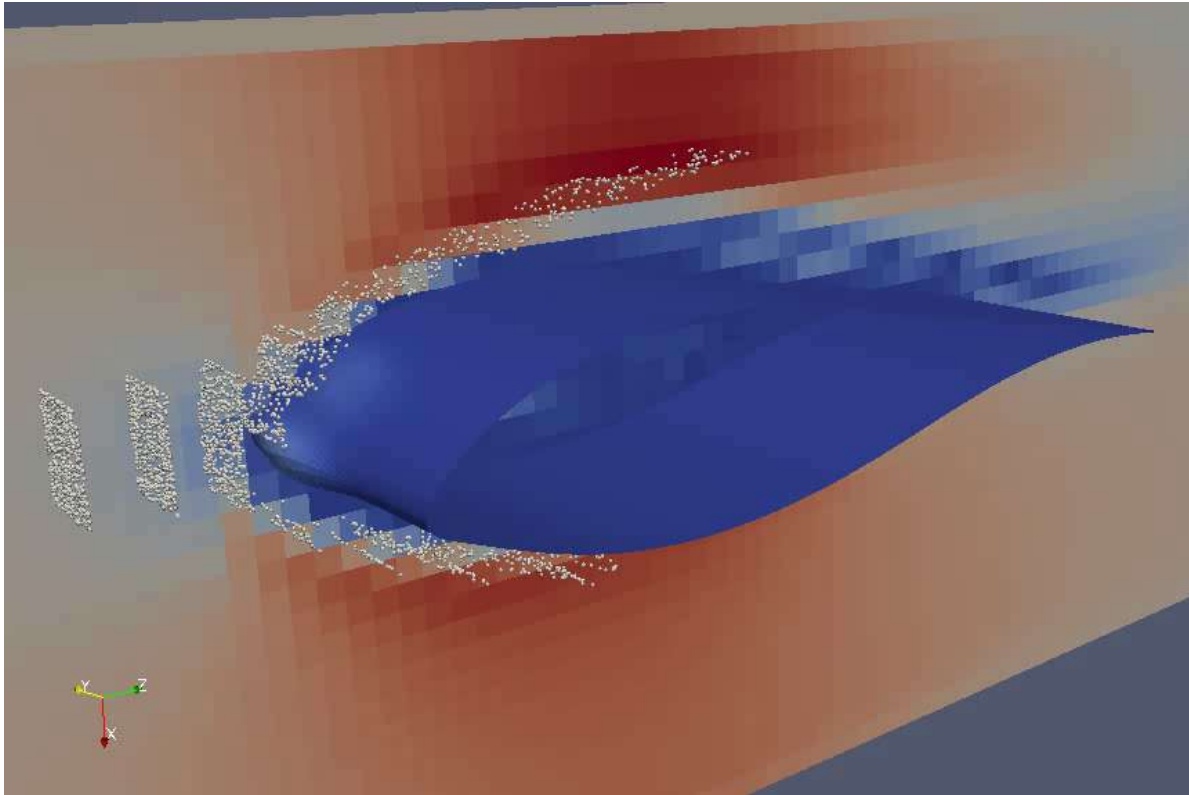
Goals



$$\frac{dM}{dt} = \alpha_1 \alpha_2 \alpha_3 \phi u A$$

- Develop tool to model simultaneously flow and ice accretion
 - Efficient (relative)
 - Flexible
 - » Avoid/fewer model coefficients
 - » Complex/moving geometries
 - Combine with other modules
 - » Performance
 - » Noise

Method

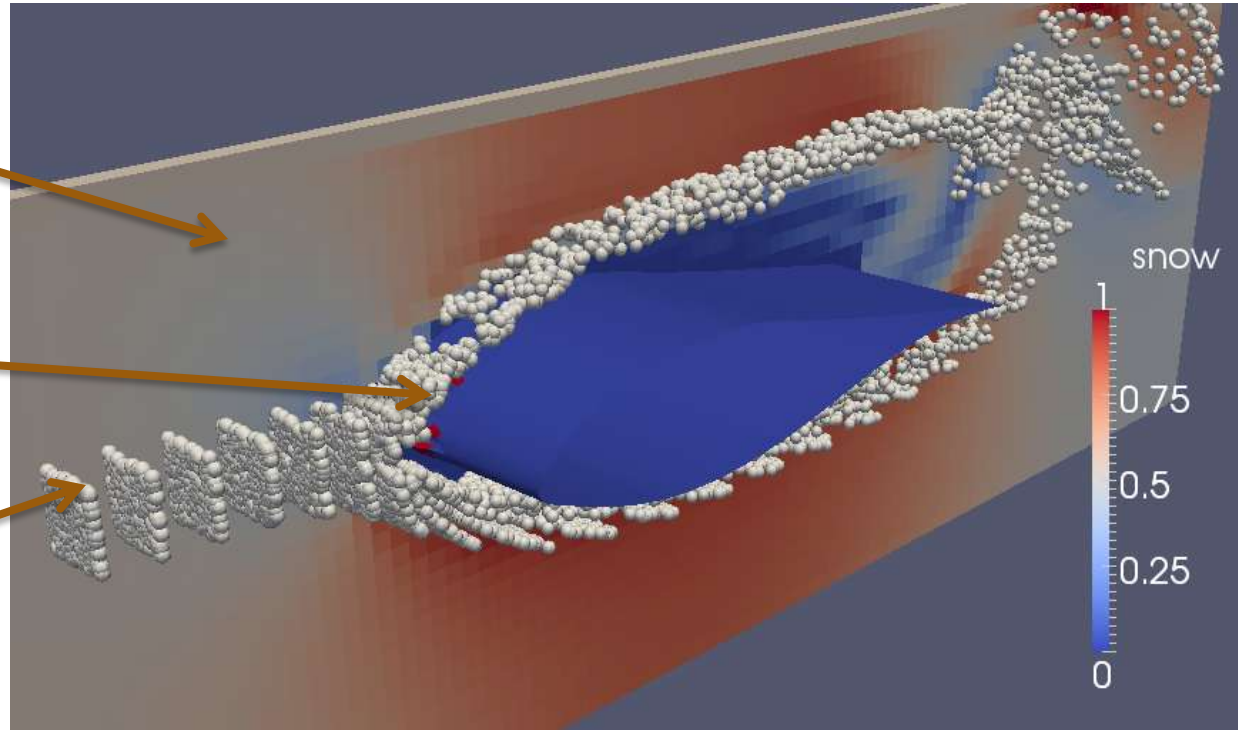


Method

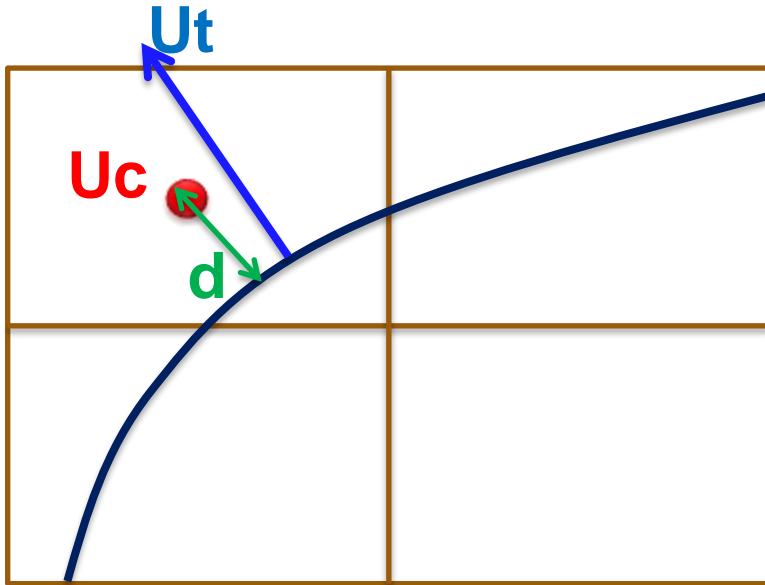
Flow: LES + Im.Bound.

Accretion: Impacting droplets freeze instantaneously

Droplets: LPT

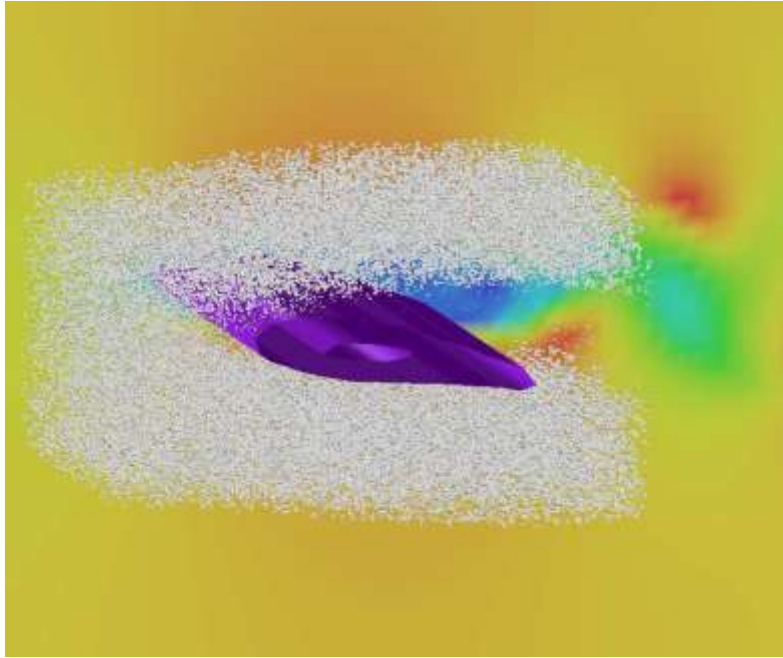


Flow



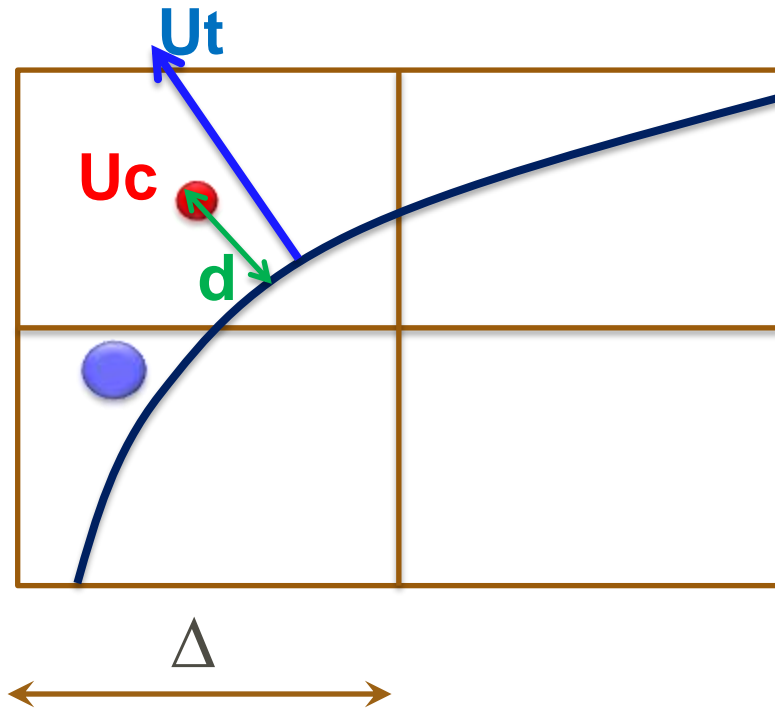
- Incompressible Navier Stokes
- Finite Differences (3rd, 4th)
- LES (implicit)
- Equidistant Cartesian grid
- Immersed Boundary

Droplet transport



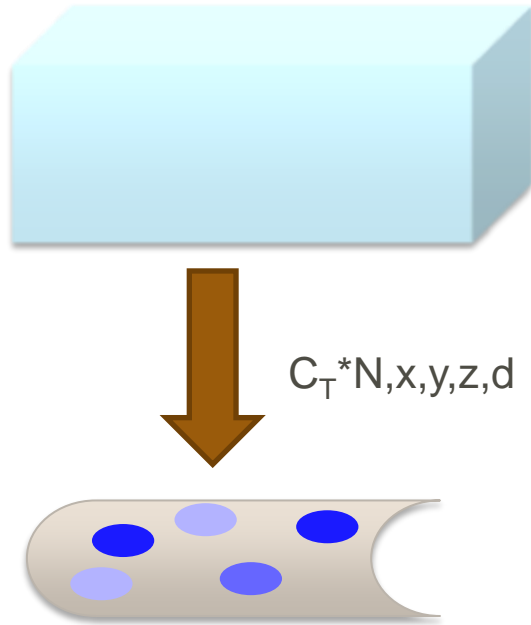
- Lagrangian Particle Tracking
- Typically low LWC
 - Only drag force
 - No collision
 - No break-up
- Release: rectangular area, random distribution
- Removal: accretion or max streamwise position
- Impact parameters logged

Ice Accretion



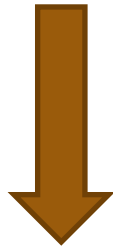
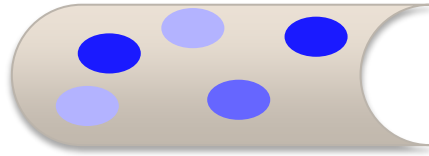
- All droplets impacting on the surface freeze instantaneously
 - Rime-ice conditions
 - For other conditions heat transfer must be included
- Distance from distance function used for IBM
 - Efficient but slightly lower accuracy
- Critical distance
 - $d_{cr} = f\Delta$

Changing the surface shape

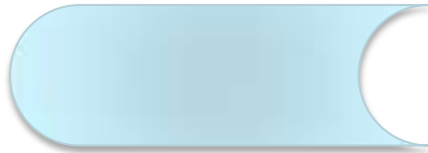


- CFD: N, x, y, z, d, m
- every N^{th} timestep
 - Can be extrapolated in time: $m_{\text{ice}} = m_{\text{ice}} * C_{\text{time}}$

Changing the surface shape

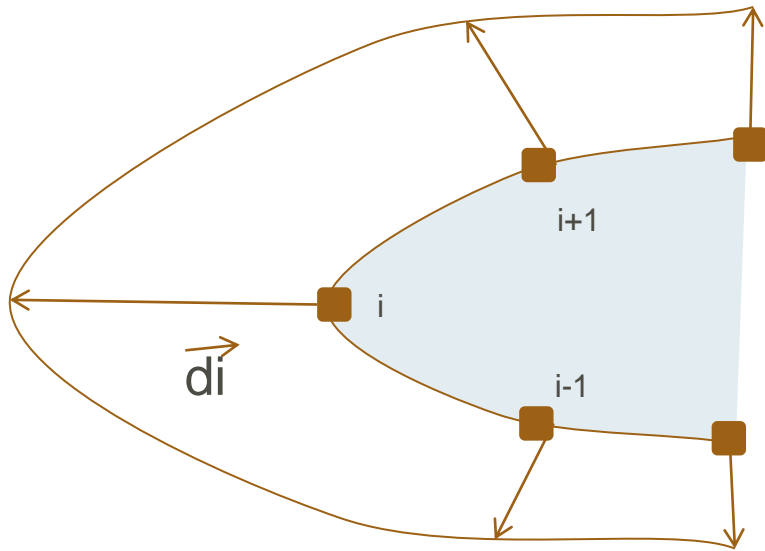


Filtering



- CFD: N, x, y, z, d, m
- every N^{th} timestep
 - Can be extrapolated in time: $m_{\text{ice}} = m_{\text{ice}} * C_{\text{time}}$
 - Trapped air can be accounted for here
- Filtering

Changing the surface shape

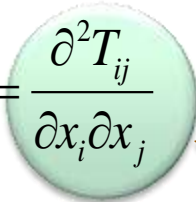


$$\vec{D}_i \approx V_{ice_i} / A_{dualcell}$$

- CFD: N, x, y, z, d, m
- every N th timestep
 - Can be extrapolated in time:
 $V_{ice} = V_{ice} * C_{time}$
 - Trapped air can be accounted for here
- Filtering
- Iterative algorithm
 - Towards outer normal
 - Assure added V_{ice}
 - Only a few iterations needed

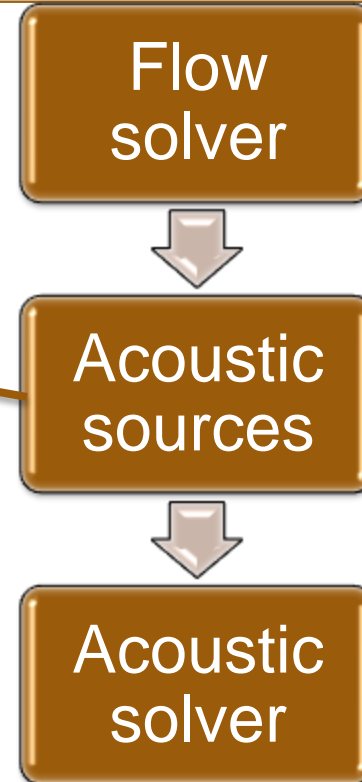
Noise computations

- Hybrid-method (Lighthill)

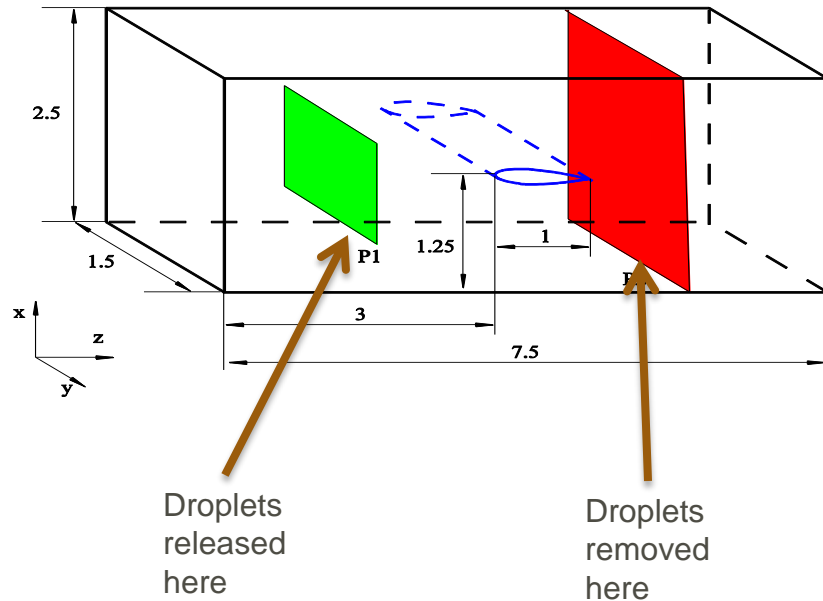
$$\frac{1}{c^2} \frac{\partial p'^2}{\partial t^2} - \nabla^2 p' = \frac{\partial^2 T_{ij}}{\partial x_i \partial x_j}$$


- Advantages

- Dedicated solvers for flow & acoustics
- Acoustic sources can be iterated
- Possibility of different
 - » Mesh
 - » Computed physical time



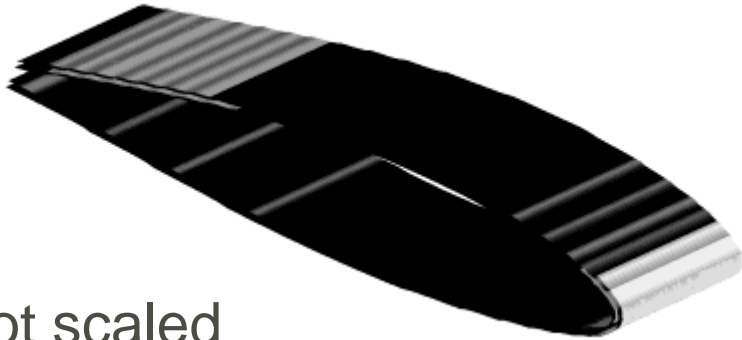
Case set-up



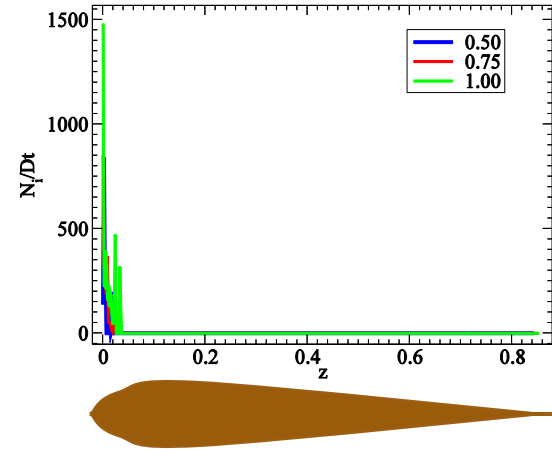
- 'In-fog icing event 2' [Hochart2008]

Parameter	Value
Profile	NACA 63415
Angle of attack	3°
LWC	0.37g/m ³
MVD	27.6 μm
Vrel	18.7 m/s
Re	2.49e5
Time	10.6 min
Mass of accreted ice	24±1.75 g

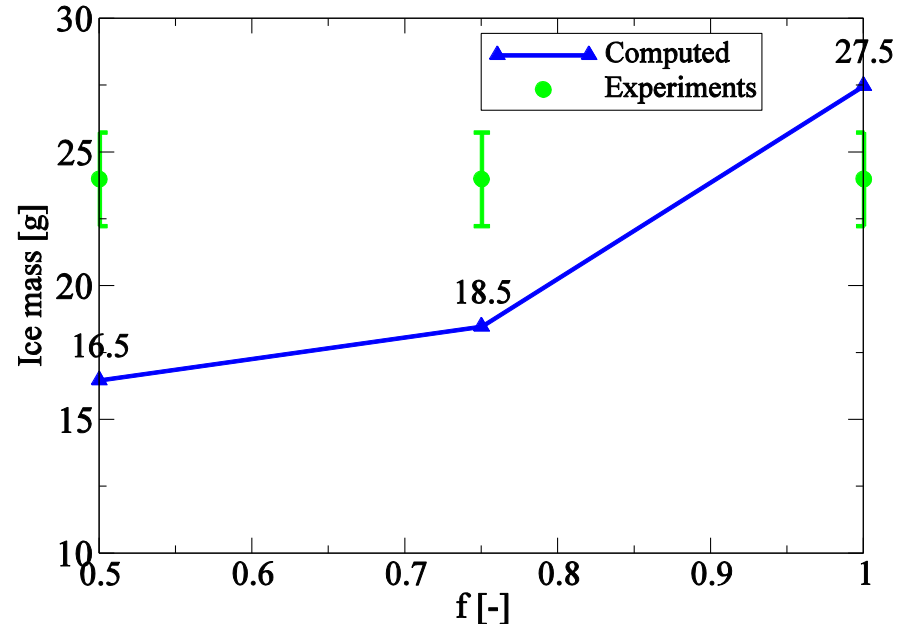
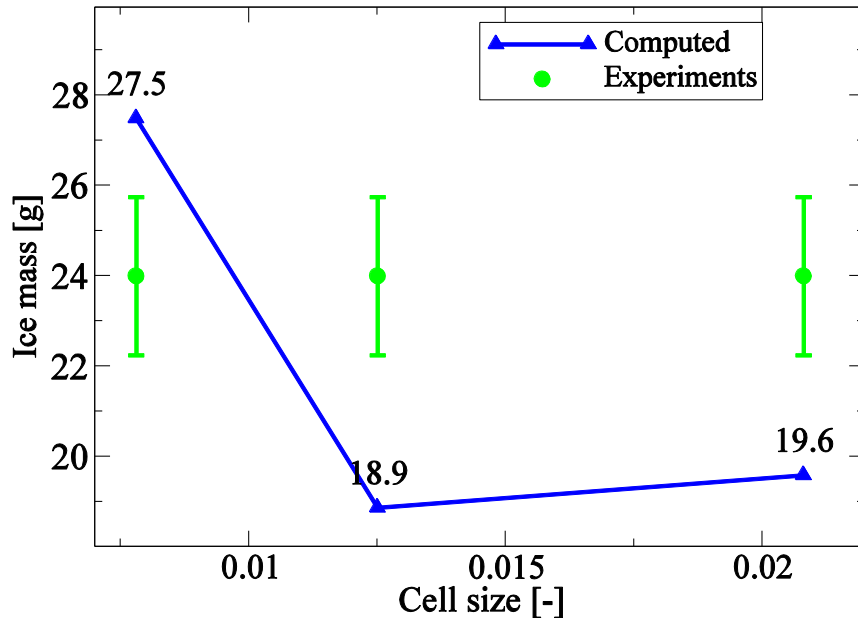
Ice distribution



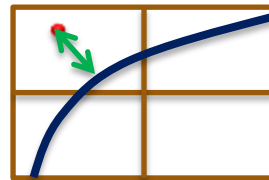
Not scaled



Sensitivity



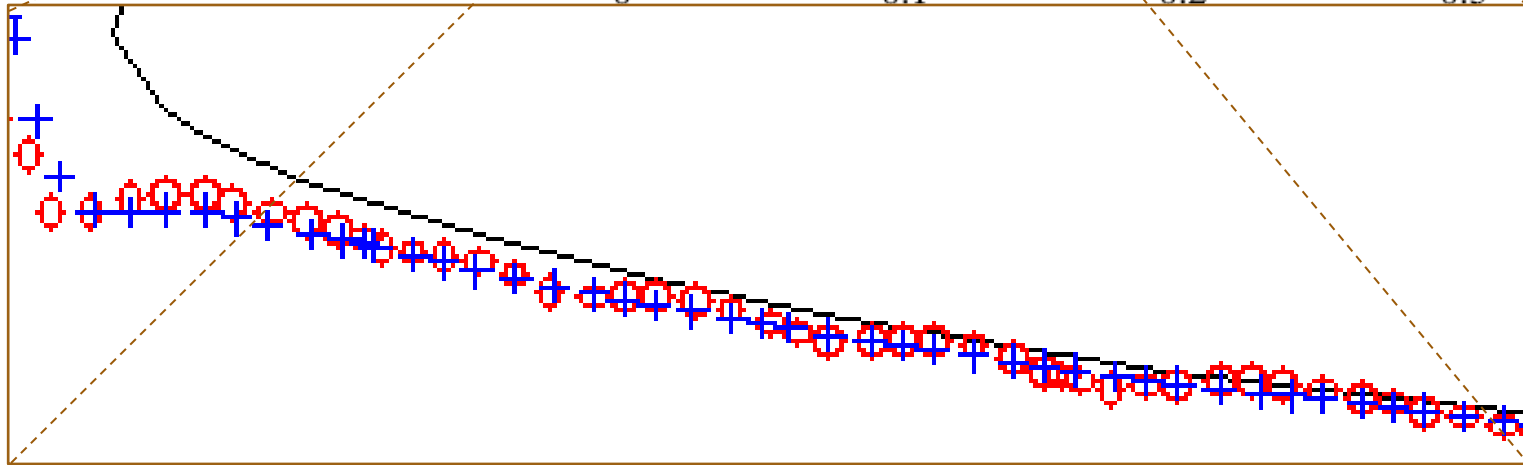
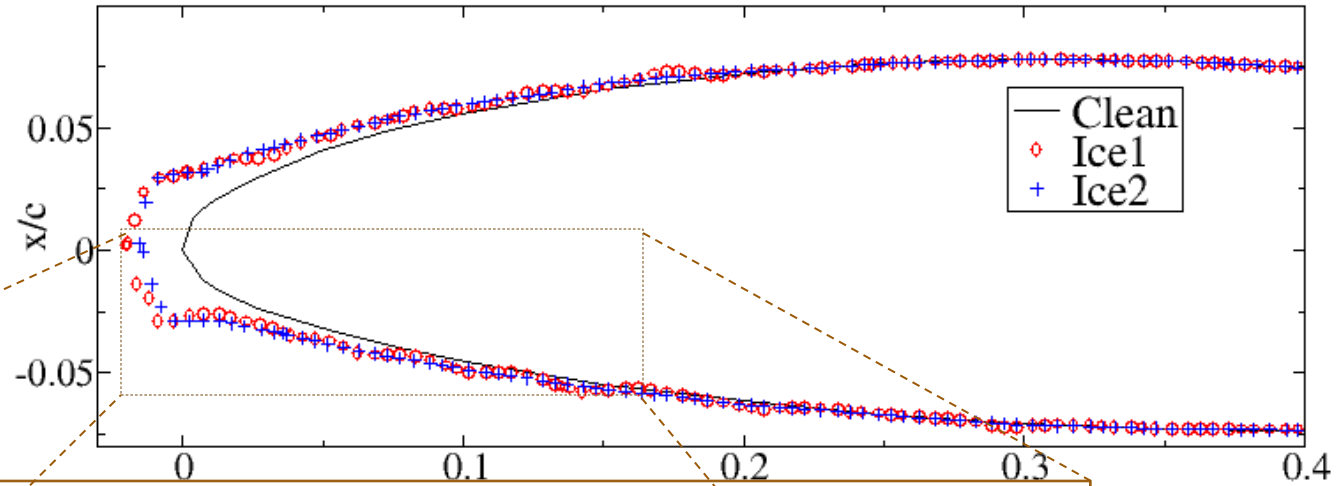
Grid



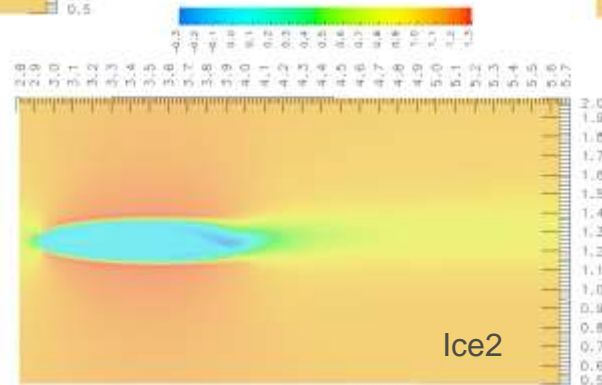
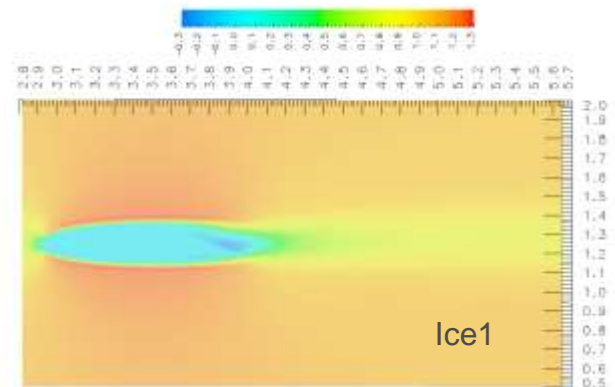
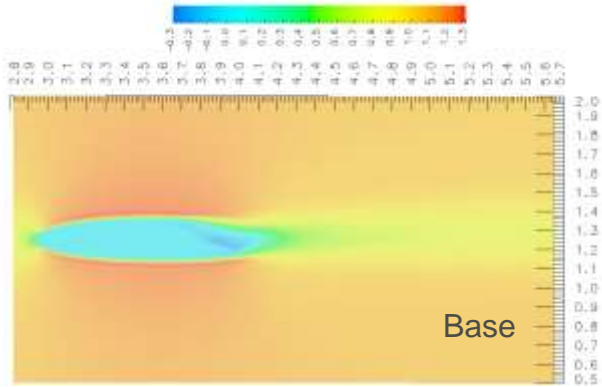
Model parameter

$$d_{cr} = f\Delta$$

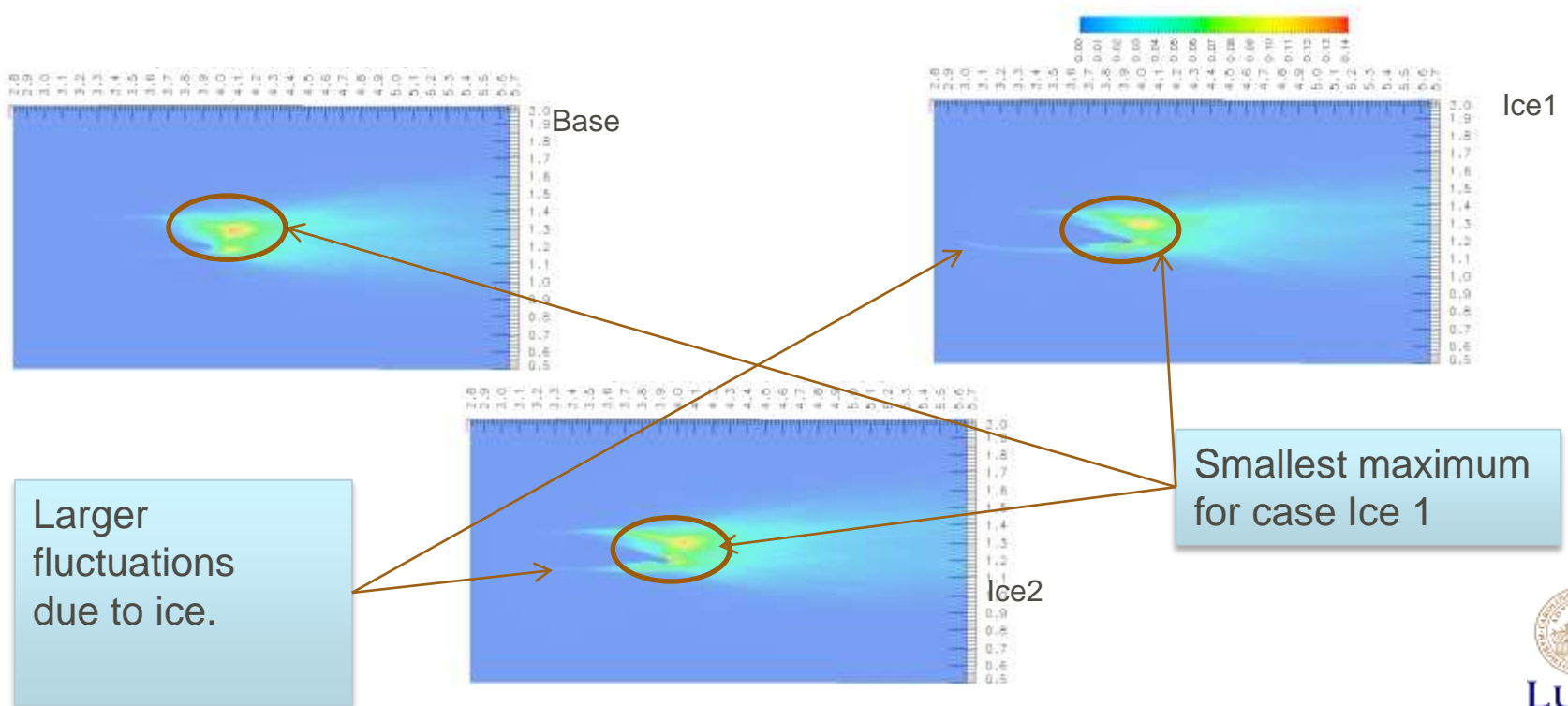
Ice distribution



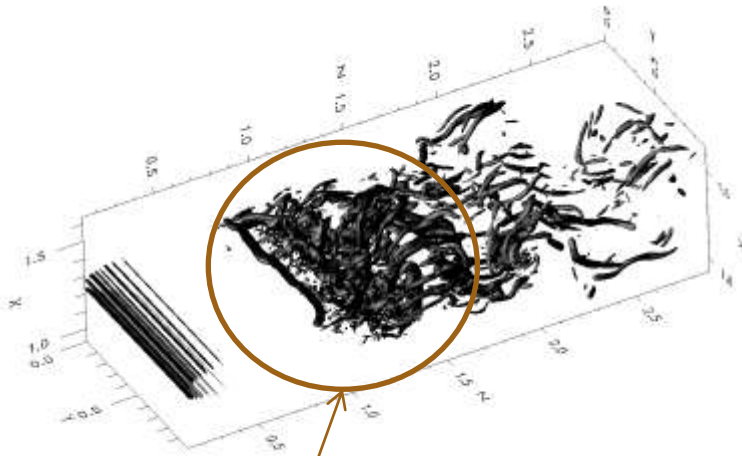
Average velocity



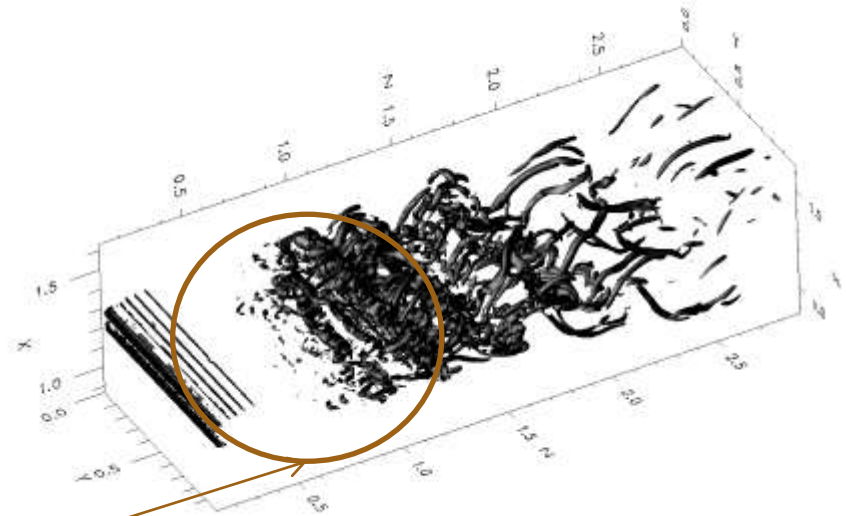
RMS velocity



Vortical structures ($\lambda 2$)

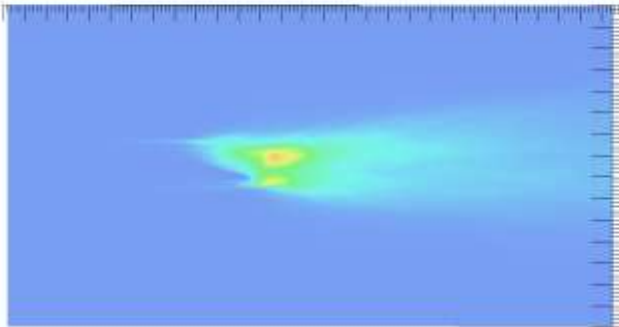
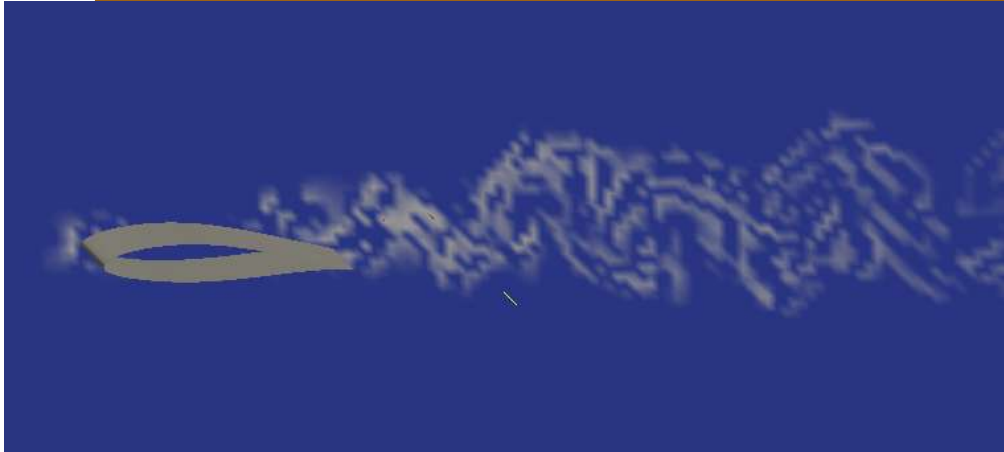


Long
structure



Small
vortices

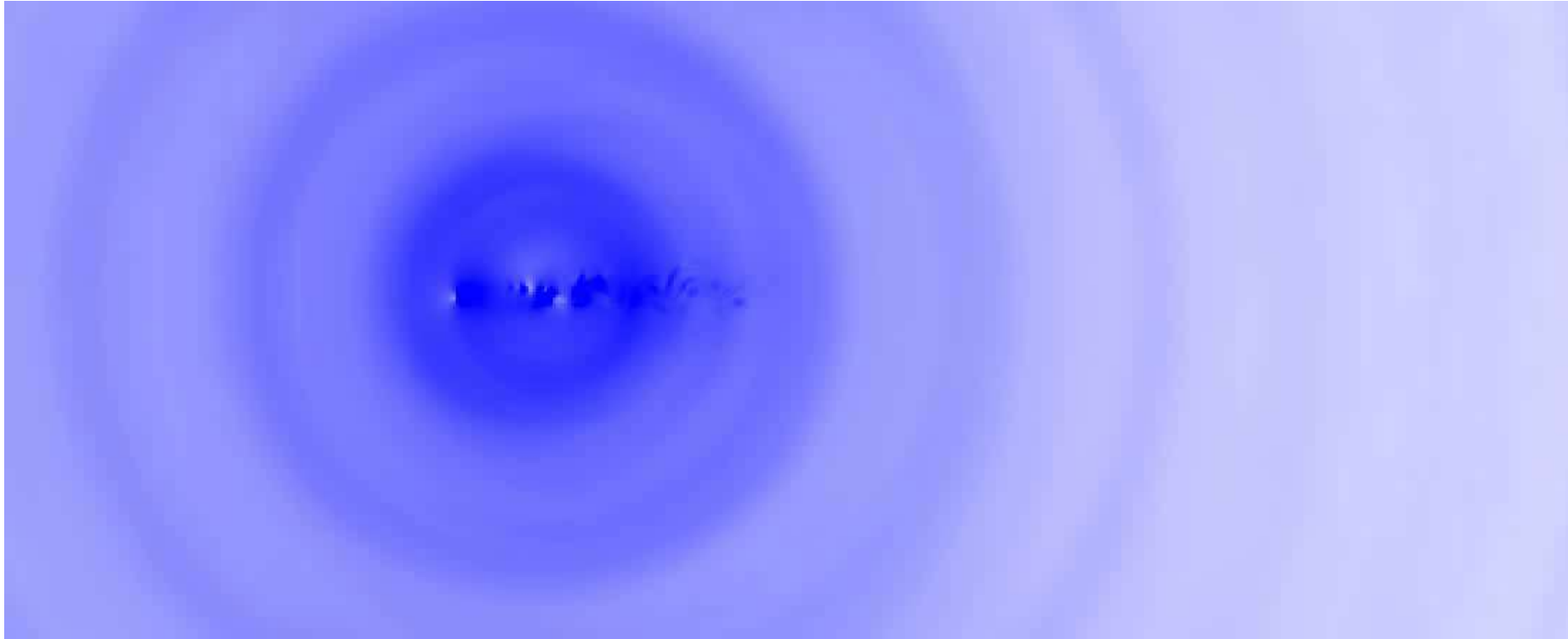
Acoustic sources



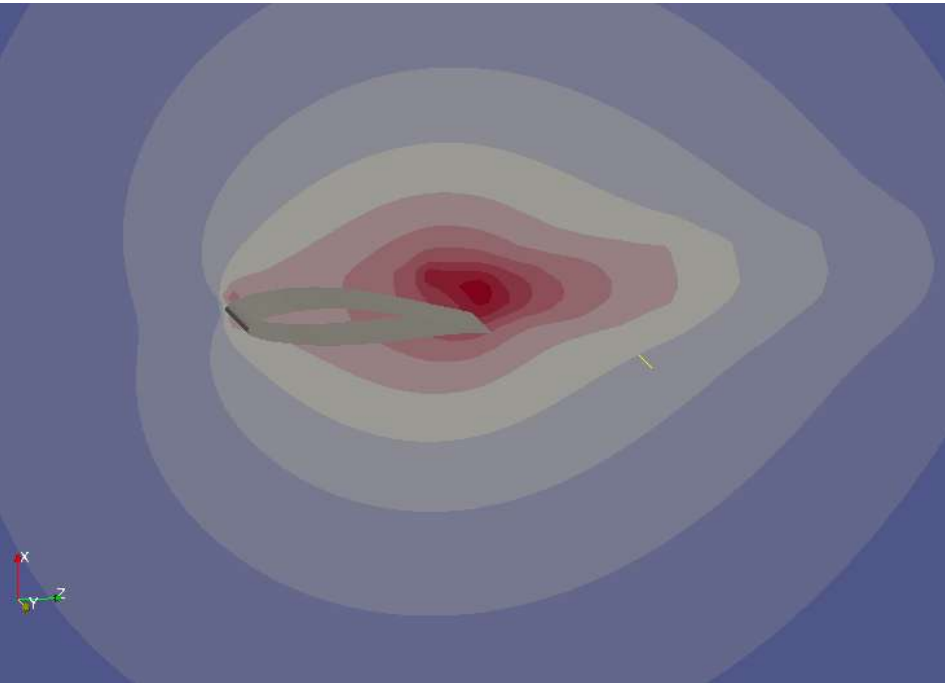
- Lighthill source term
 - Dipoles and monopoles can be computed as well

- Strongest sources in the near wake region

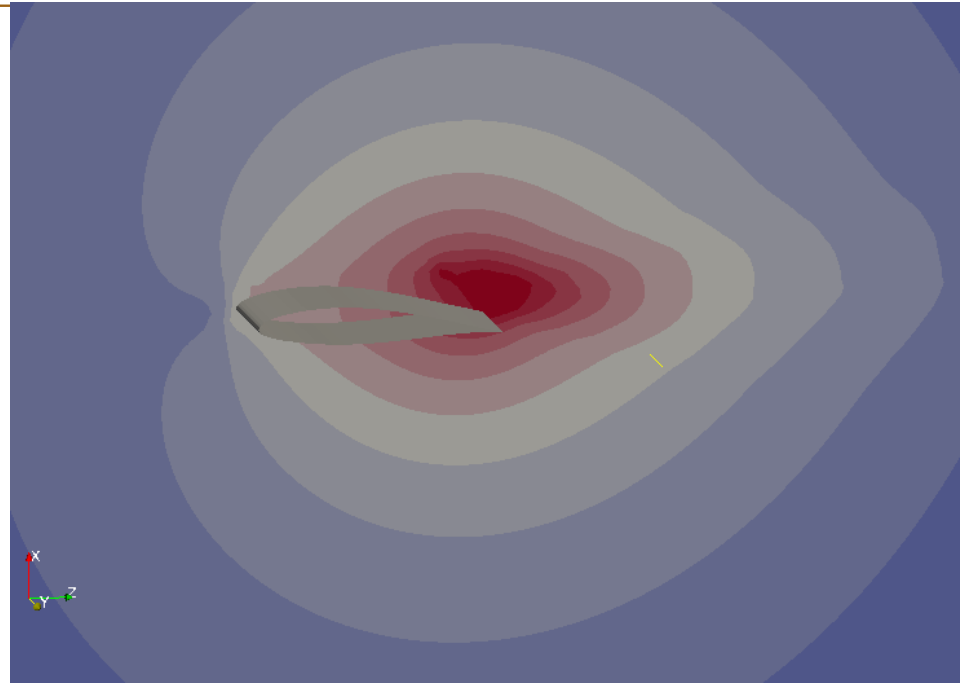
Acoustic density fluctuations



RMS Acoustic Density Fluctuation

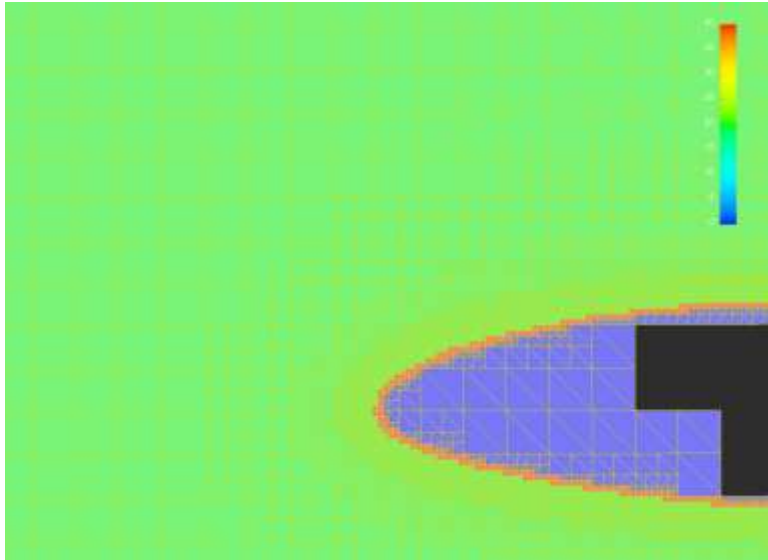


Clean



With ice accretion

Future work



- Other icing conditions
 - Add heat transfer
- Acoustics
 - Account for monopoles and dipoles as well
- Improve efficiency
 - Oct-tree mesh

Thank you!

